

Linear Algebra, Optimization, and Linear Regression

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$$\begin{bmatrix} 1 & x+1 & x^2+1 \\ 1 & y+1 & y^2+1 \\ 1 & z+1 & z^2+1 \end{bmatrix} x = \sum_{i=1}^n x_i v_i = x_1 v_1 + x_2 v_2 + \dots + x_n v_n \quad v_k = y_k - \sum_{i=1}^{k-1} (v_i, y_k) v_i$$

$$F(x) = F(x^*) + \nabla F(x^*)^T (x - x^*) + \frac{1}{2} (x - x^*)^T \nabla^2 F(x^*) (x - x^*) + \dots$$

$$\frac{\mathbf{p}^T \nabla^2 F(\mathbf{x}) \mathbf{p}}{\|\mathbf{p}\|^2} \quad \nabla F(\mathbf{x}) = \left[\frac{\partial}{\partial x_1} F(\mathbf{x}) \quad \frac{\partial}{\partial x_2} F(\mathbf{x}) \quad \dots \quad \frac{\partial}{\partial x_n} F(\mathbf{x}) \right]^T$$

$$\begin{bmatrix} p_1^T \\ p_2^T \\ \vdots \\ p_Q^T \end{bmatrix}$$

LINEAR ALGEBRA

$$W^{new} = (1 - \gamma) W^{old} + \alpha t_q P_c^T$$

$$W^{new} = W^{old} + \alpha (t_q - a_c) P_c^T$$

$$W^{new} = W^{old} + \alpha \beta_q P_c^T$$

$$\begin{bmatrix} \frac{\partial}{\partial x_1} F(\mathbf{x}) & \frac{\partial}{\partial x_1 \partial x_2} F(\mathbf{x}) & \dots & \frac{\partial}{\partial x_1 \partial x_n} F(\mathbf{x}) \\ \frac{\partial}{\partial x_2} F(\mathbf{x}) & \frac{\partial}{\partial x_2^2} F(\mathbf{x}) & \dots & \frac{\partial}{\partial x_2 \partial x_n} F(\mathbf{x}) \\ \vdots & \vdots & \ddots & \vdots \\ \frac{\partial}{\partial x_n} F(\mathbf{x}) & \frac{\partial}{\partial x_n \partial x_1} F(\mathbf{x}) & \dots & \frac{\partial}{\partial x_n^2} F(\mathbf{x}) \end{bmatrix}$$

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Presentation Outline

- 1 Introduction and Background
- 2 Review of Linear Algebra
- 3 Optimization
- 4 Linear Regression
- 5 Conclusion

Why linear algebra is important?

- Linear algebra is at the heart of machine learning
- Many advanced linear algebra techniques are important to machine learning algorithms
- Matrices are how computers make sense of data

Why optimization is important?

- Most machine learning frameworks focus on optimization
- As economists, we often want to view algorithms through the lens of optimization

Why re-introduce linear regression?

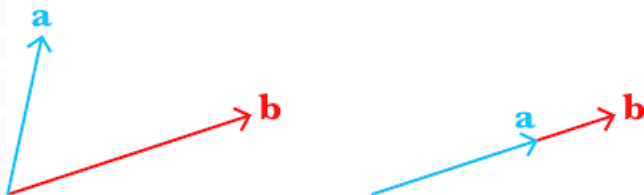
- Machine learning view on linear regression focuses on optimization
- Linear regression is a common framework in econometrics and provides a lens through which to see machine learning
- Most undergrad econometric classes don't focus on matrix algebra

Matrix Multiplication

$$\begin{bmatrix} a_1 & a_2 & a_3 \\ a_4 & a_5 & a_6 \\ a_7 & a_8 & a_9 \end{bmatrix} \begin{bmatrix} b_1 & b_2 & b_3 \\ b_4 & b_5 & b_6 \\ b_7 & b_8 & b_9 \end{bmatrix} = \begin{bmatrix} c_1 & c_2 & c_3 \\ c_4 & c_5 & c_6 \\ c_7 & c_8 & c_9 \end{bmatrix}$$

Linear Independence

- A set of vectors $\{v_i\}_{i=1}^n$ is linearly independent if the vector equation $x_1 v_1 \dots x_n v_n = 0$ has only the trivial solution $x=0$



Linear Independence Example

- Are the following vectors linearly independent?

$$\begin{bmatrix} 2 & -4 & 1 \\ 2 & 6 & 0 \\ 1 & 5 & 0 \end{bmatrix}$$

(1)

Linear Independence Example

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$$\begin{bmatrix} 2 & -4 & 1 \\ 2 & 6 & 0 \\ 1 & 5 & 0 \end{bmatrix} \quad (1)$$

$$\begin{bmatrix} 2 & 15 & 3 \\ 5 & 7 & 9 \\ 4 & 30 & 6 \end{bmatrix} \quad (2)$$

Rank

- A matrix's rank is the number of linearly independent rows
- The rank of a matrix can be found by row-reducing and finding number of pivot points
- Only matrices of full rank are invertible. Why is this important?

$$\begin{array}{ccc} \begin{bmatrix} 1 & 2 & 1 \\ -2 & -3 & 1 \\ 3 & 5 & 0 \end{bmatrix} & \xrightarrow{2R_1+R_2 \rightarrow R_2} & \begin{bmatrix} 1 & 2 & 1 \\ 0 & 1 & 3 \\ 3 & 5 & 0 \end{bmatrix} & \xrightarrow{-3R_1+R_3 \rightarrow R_3} & \begin{bmatrix} 1 & 2 & 1 \\ 0 & 1 & 3 \\ 0 & -1 & -3 \end{bmatrix} \\ & \xrightarrow{R_2+R_3 \rightarrow R_3} & \begin{bmatrix} 1 & 2 & 1 \\ 0 & 1 & 3 \\ 0 & 0 & 0 \end{bmatrix} & \xrightarrow{-2R_2+R_1 \rightarrow R_1} & \begin{bmatrix} 1 & 0 & -5 \\ 0 & 1 & 3 \\ 0 & 0 & 0 \end{bmatrix}. \end{array}$$

Inverse Definition

- A square matrix's inverse is the matrix that when multiplied by the matrix is the identity
- While most matrix multiplication is not commutative, inverse multiplication is
- Singular matrices have no inverse

$$AA^{-1} = A^{-1}A = I \quad (3)$$

Finding an Inverse

- Method 1: Augment matrix with identity matrix, and row reduce original matrix while applying steps to augmented matrix
- Method 2: Multiple inverse of absolute value of determinant by adjoint matrix

$$A^{-1} = \frac{1}{|A|} \begin{bmatrix} \begin{vmatrix} a_{22} & a_{23} \\ a_{32} & a_{33} \end{vmatrix} & \begin{vmatrix} a_{13} & a_{12} \\ a_{33} & a_{32} \end{vmatrix} & \begin{vmatrix} a_{12} & a_{13} \\ a_{22} & a_{23} \end{vmatrix} \\ \begin{vmatrix} a_{23} & a_{21} \\ a_{33} & a_{31} \end{vmatrix} & \begin{vmatrix} a_{11} & a_{13} \\ a_{31} & a_{33} \end{vmatrix} & \begin{vmatrix} a_{13} & a_{11} \\ a_{23} & a_{21} \end{vmatrix} \\ \begin{vmatrix} a_{21} & a_{22} \\ a_{31} & a_{32} \end{vmatrix} & \begin{vmatrix} a_{12} & a_{11} \\ a_{32} & a_{31} \end{vmatrix} & \begin{vmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{vmatrix} \end{bmatrix}$$

Usefulness of Inverses

- Matrix inverses can be used to solve systems of equations
- Crucial for econometrics and specific machine learning tasks

Determinants

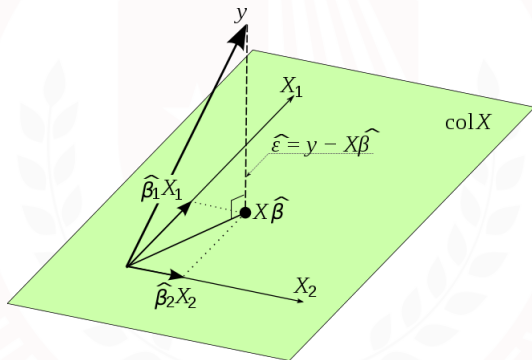
- Determinants have four properties:
 - The determinant of the identity matrix is 1
 - Exchange of two rows multiplies determinant by -1
 - Multiplying a row by a number multiplies the determinant by this number
 - Adding to a row a multiple of another row does not change the determinant

Eigenvalues and Eigenvectors

- Eigenvectors are vectors that when multiplied by a matrix produce themselves times a constant
- The constant is the eigenvalue
- Eigendecomposition is incredibly useful for PCA

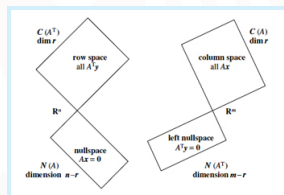
$$A\vec{v} = \lambda\vec{v} \quad (4)$$

Projection



Spaces

- a vector is said to be in space V if for scalar c , $c\vec{a} \in V$ and for $\vec{a} \in V$ and $\vec{b} \in V$, $\vec{a} + \vec{b} \in V$



Norms

- Norms have three properties
 - Subadditivity: $p(x + y) \leq p(x) + p(y) \forall x, y \in X$
 - Absolute homogeneity: $p(sx) = |s|p(x)$
 - Positive definiteness: $p(x) = 0 \Leftrightarrow x = 0$
- Why are these useful? What might a function that is a norm look like?

Norms

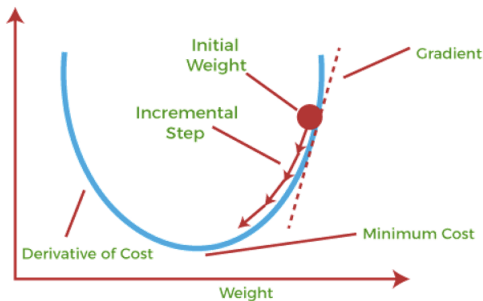
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- Why are these useful? What might a function that is a norm look like?
- Euclidean Norm: $\|x\|_2 = \sqrt{x_1^2 + \dots + x_n^2}$
- Taxicab Norm: $\|x\|_1 = \sum_{i=1}^n |x_i|$
- P-norm $\|x\|_p = \left(\sum_{i=1}^n |x_i|^p\right)^{\frac{1}{p}}$

Analytic Optimization

- Analytic optimization is the most well known to economists
- It involves finding the maximum of a convex function
- Analytic optimization can only be done for functions with analytic maximums

Gradient Descent

Understanding Gradient Descent

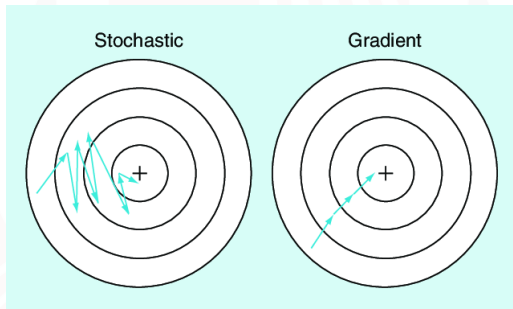


$$f(x) = x^2 - 4x + 3$$
$$x = x - \text{learning_rate} * \text{grad}$$

Stochastic Gradient Descent

- Take gradient for random observation i and take step in that direction

$$\theta' = \theta - \alpha \nabla f_i(\theta) \quad (5)$$



Newton's Method

$$\theta' = \theta - \frac{f'(\theta)}{f''(\theta)} \quad (6)$$

Deriving Least Squares with Matrix

$$y = \beta X + u \quad (7)$$

$$\min_{\beta} \sum_{t=1}^T [y_t - \sum_{i=1}^n \beta_i x_{ti}]^2 \quad (8)$$

$$\min_{\beta} \sum_{i=1}^N [y - X\beta]^2 \quad (9)$$

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$$X'y - X'X\hat{\beta} = 0 \quad (11)$$

$$X'y = X'X\hat{\beta} = 0 \quad (12)$$

$$\hat{\beta} = (X'X)^{-1}(X'y) \quad (13)$$

Least Squares Asymptotics

$$E(\hat{\beta}) = (X'X)^{-1}(X'y) = \quad (14)$$

$$(X'X)^{-1}(X'(X\beta + u)) = \quad (15)$$

$$(X'X)^{-1}X'X\beta + (X'X)^{-1}X'u = \quad (16)$$

$$\beta + (X'X)^{-1}X'u \quad (17)$$

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$$E(\hat{\beta}) = \beta \quad (18)$$

Least Squares Standard Error

$$D(\hat{\beta}) = E(\hat{\beta} - E\hat{\beta})(\hat{\beta} - E\hat{\beta})' = \quad (19)$$

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$$\sigma^2(X'X)^{-1}X'X(X'X)^{-1} = \sigma^2(X'X)^{-1} \quad (24)$$

$$\text{Var}\hat{\beta}_i = \sigma^2(X'X)^{-1}_{ii} \quad (25)$$

Assumptions and Violations of Least Squares Asymptotics

- What happens if the x -values are correlated with the error term?

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$$E(\hat{\beta}) = (X'X)^{-1}X'X\beta + (X'X)^{-1}X'u = \quad (26)$$

$$\beta + (X'X)^{-1}X'u \neq \beta \quad (27)$$

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- What happens if the y values are correlated with the error term?

Derivation of Maximum Likelihood Estimator of Least Squares

$$y_t = X_t\beta + u_t, u_t \sim iidN(0, \sigma^2) \quad (28)$$

$$L(y|\beta, \sigma) = \prod_{t=1}^T \frac{1}{\sqrt{2\pi\sigma}} \exp\left\{-\frac{1}{2\sigma^2}(y - X_t\beta)^2\right\} \quad (29)$$

$$\ln(L(y|\beta, \sigma)) = \sum_{t=1}^T \left[-\frac{1}{2} \ln(2\pi) - \ln(\sigma) - \frac{1}{2\sigma^2}(y_t - X_t\beta)^2 \right] \quad (30)$$

- This is maximized by minimizing the sum of squared errors

Algorithm for Solving Least Squares using Maximum Likelihood

- Start with cost function
- Minimize
- How to find standard error?

Algorithm for Solving Least Squares using Maximum Likelihood

- Start with cost function
- Minimize
- How to find standard error?
- Hessian matrix/ Information matrix
- Monte Carlo

Cost Functions

- A function you attempt to minimize within the machine learning context
- A way to measure how well your algorithm is performed
- Example: MSE, log loss
- Generally make log loss negative. Why?

LASSO

- L1 Norm
- Used to choose variables and prevent overfitting
- Sets value of some coefficients to zero

$$\min_{\beta_0, \beta_1} \{ \sum_{i=1}^N (y_i - \beta_0 - x_i^T \beta)^2 \} \text{ s.t. } \sum_{j=1}^p |\beta_j| \leq t \quad (31)$$

Ridge

- L2 norm
- Scales all coefficients based on their value for prediction
- Can perform regression even when colinearity exists

$$\min \sum_{i=1}^N (y_i - \beta_0 - x_i^T \beta)^2 \text{ s.t. } \lambda \sum_{j=1}^p |\beta_j^2| \leq t \quad (32)$$

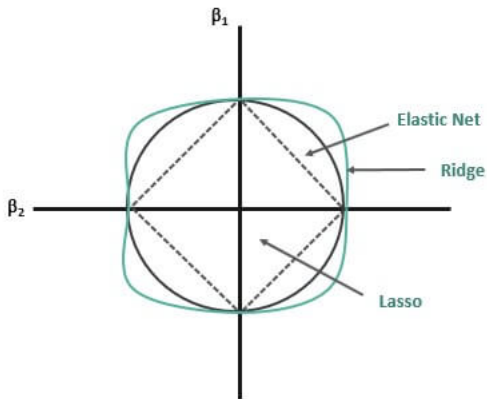
Elastic Net

- Elastic Net uses penalties on both the L_1 and L_2 norm
- Compromise between Lasso and Ridge

$$\min \sum_{i=1}^N (y_i - \beta_0 - x_i^T \beta)^2 \text{ s.t. } \lambda_2 \|\beta\|^2 \leq t_1, \lambda_1 \|\beta_1\| \leq t_2 \quad (33)$$

Visualization

Elastic net-Diagrammatic Representation



Thank You So Much!

